# 74LVC1T45-Q100; 74LVCH1T45-Q100

**Dual supply translating transceiver; 3-state** Rev. 4 — 1 December 2020

**Product data sheet** 

## 1. General description

The 74LVC1T45-Q100; 74LVCH1T45-Q100 are single bit, dual supply transceivers with 3-state outputs that enable bidirectional level translation. They feature two 1-bit input-output ports (A and B), a direction control input (DIR) and dual supply pins ( $V_{CC(A)}$  and  $V_{CC(B)}$ ). Both  $V_{CC(A)}$  and  $V_{CC(B)}$  can be supplied with any voltage between 1.2 V and 5.5 V. This flexibility makes the device suitable for translating between any of the low voltage nodes (1.2 V, 1.5 V, 1.8 V, 2.5 V, 3.3 V and 5.0 V). Pins A and DIR are referenced to  $V_{CC(A)}$  and pin B is referenced to  $V_{CC(B)}$ . A HIGH on DIR allows transmission from A to B and a LOW on DIR allows transmission from B to A.

The devices are fully specified for partial power-down applications using I<sub>OFF</sub>. The I<sub>OFF</sub> circuitry disables the output, preventing any damaging backflow current through the device when it is powered down. In suspend mode when either V<sub>CC(A)</sub> or V<sub>CC(B)</sub> are at GND level, both A port and B port are in the high-impedance OFF-state.

Active bus hold circuitry in the 74LVCH1T45-Q100 holds unused or floating data inputs at a valid logic level.

This product has been qualified to the Automotive Electronics Council (AEC) standard Q100 (Grade 1) and is suitable for use in automotive applications.

# 2. Features and benefits

- Automotive product qualification in accordance with AEC-Q100 (Grade 1)
  - Specified from -40 °C to +85 °C and from -40 °C to +125 °C
- Wide supply voltage range:
  - V<sub>CC(A)</sub>: 1.2 V to 5.5 V
  - V<sub>CC(B)</sub>: 1.2 V to 5.5 V
- High noise immunity
- Complies with JEDEC standards:
  - JESD8-7 (1.2 V to 1.95 V)
  - JESD8-5 (1.8 V to 2.7 V)
  - JESD8C (2.7 V to 3.6 V)
  - JESD36 (4.5 V to 5.5 V)
- ESD protection:
  - HBM JESD22-A114F Class 3A exceeds 4000 V
  - CDM JESD22-C101E exceeds 1000 V
- Maximum data rates:
  - 420 Mbps (3.3 V to 5.0 V translation)
  - 210 Mbps (translate to 3.3 V))
  - 140 Mbps (translate to 2.5 V)
  - 75 Mbps (translate to 1.8 V)
  - 60 Mbps (translate to 1.5 V)
- Suspend mode
- Latch-up performance exceeds 100 mA per JESD 78 Class II
- ±24 mA output drive (V<sub>CC</sub> = 3.0 V)
- Inputs accept voltages up to 5.5 V
- Low power consumption: 16 µA maximum I<sub>CC</sub>
- I<sub>OFF</sub> circuitry provides partial Power-down mode operation

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# 3. Ordering information

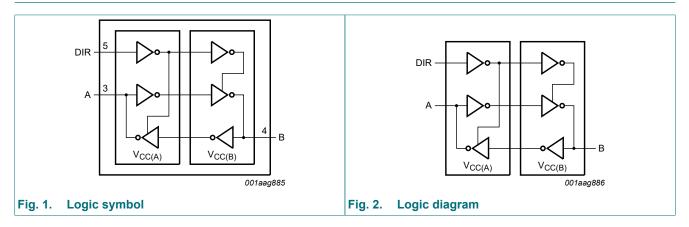
Type number	Package							
	Temperature range	Name	Description	Version				
74LVC1T45GW-Q100	-40 °C to +125 °C	SC-88	plastic surface-mounted package; 6 leads	SOT363				
74LVCH1T45GW-Q100	_							
74LVC1T45GM-Q100	-40 °C to +125 °C	XSON6	plastic extremely thin small outline package; no leads; 6 terminals; body 1 × 1.45 × 0.5 mm	SOT886				

# 4. Marking

Table 2. Marking						
Type number	Marking code [1]					
74LVC1T45GW-Q100	V5					
74LVCH1T45GW-Q100	X5					
74LVC1T45GM-Q100	V5					

[1] The pin 1 indicator is located on the lower left corner of the device, below the marking code.

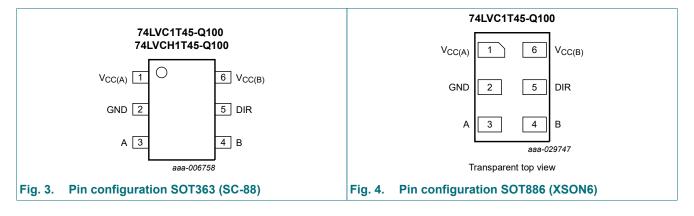
# 5. Functional diagram



74LVC\_LVCH1T45\_Q100

# 6. Pinning information

## 6.1. Pinning



## 6.2. Pin description

Table 3. Pin description							
Symbol	Pin	Description					
V <sub>CC(A)</sub>	1	supply voltage port A and DIR					
GND	2	ground (0 V)					
A	3	data input or output					
В	4	data input or output					
DIR	5	direction control					
V <sub>CC(B)</sub>	6	supply voltage port B					

# 7. Functional description

#### Table 4. Function table

H = HIGH voltage level; L = LOW voltage level; X = don't care; Z = high-impedance OFF-state.

Supply voltage	Input	Input/output [1]			
V <sub>CC(A)</sub> , V <sub>CC(B)</sub>	DIR	Α	В		
1.2 V to 5.5 V	L	A = B	input		
1.2 V to 5.5 V	Н	input	B = A		
GND [2]	Х	Z	Z		

[1] The input circuit of the data I/O is always active.

[2] When either  $V_{CC(A)} \text{ or } V_{CC(B)}$  is at GND level, the device goes into suspend mode.

# 8. Limiting values

#### Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions		Min	Max	Unit
V <sub>CC(A)</sub>	supply voltage A			-0.5	+6.5	V
V <sub>CC(B)</sub>	supply voltage B			-0.5	+6.5	V
I <sub>IK</sub>	input clamping current	V <sub>1</sub> < 0 V		-50	-	mA
VI	input voltage		[1]	-0.5	+6.5	V
I <sub>OK</sub>	output clamping current	V <sub>O</sub> < 0 V		-50	-	mA
Vo	output voltage	Active mode	[1] [2] [3]	-0.5	V <sub>CCO</sub> + 0.5	V
		Suspend or 3-state mode	[1]	-0.5	+6.5	V
I <sub>O</sub>	output current	$V_{O} = 0 V$ to $V_{CCO}$	[2]	-	±50	mA
I <sub>CC</sub>	supply current	I <sub>CC(A)</sub> or I <sub>CC(B)</sub>		-	100	mA
I <sub>GND</sub>	ground current			-100	-	mA
T <sub>stg</sub>	storage temperature			-65	+150	°C
P <sub>tot</sub>	total power dissipation	T <sub>amb</sub> = -40 °C to +125 °C	[4]	-	250	mW

[1] The minimum input voltage ratings and output voltage ratings may be exceeded if the input and output current ratings are observed.

[2]  $V_{CCO}$  is the supply voltage associated with the output port.

[3] V<sub>CCO</sub> + 0.5 V should not exceed 6.5 V.

For SOT363 (SC-88) package: P<sub>tot</sub> derates linearly with 3.7 mW/K above 83 °C.
 For SOT886 (XSON6) package: P<sub>tot</sub> derates linearly with 3.3 mW/K above 74 °C.

# 9. Recommended operating conditions

#### Table 6. Recommended operating conditions

Symbol	Parameter	Conditions		Min	Мах	Unit
V <sub>CC(A)</sub>	supply voltage A			1.2	5.5	V
V <sub>CC(B)</sub>	supply voltage B			1.2	5.5	V
VI	input voltage			0	5.5	V
Vo	output voltage	Active mode	[1]	0	V <sub>cco</sub>	V
		Suspend or 3-state mode		0	5.5	V
T <sub>amb</sub>	ambient temperature			-40	+125	°C
Δt/ΔV	input transition rise and fall rate	V <sub>CCI</sub> = 1.2 V	[2]	-	20	ns/V
		V <sub>CCI</sub> = 1.4 V to 1.95 V		-	20	ns/V
		V <sub>CCI</sub> = 2.3 V to 2.7 V		-	20	ns/V
		V <sub>CCI</sub> = 3 V to 3.6 V		-	10	ns/V
		V <sub>CCI</sub> = 4.5 V to 5.5 V		-	5	ns/V

[1] V<sub>CCO</sub> is the supply voltage associated with the output port.

[2] V<sub>CCI</sub> is the supply voltage associated with the input port.

# **10. Static characteristics**

## Table 7. Typical static characteristics at T<sub>amb</sub> = 25 °C

At recommended operating conditions; voltages are referenced to GND (ground = 0 V). [1] [2]

Symbol	Parameter	Conditions		Min	Тур	Max	Unit	
V <sub>OH</sub>	HIGH-level output voltage	$V_{I} = V_{IH}$ or $V_{IL}$ ; $I_{O} = -3$ mA; $V_{CCO} = 1.2$ V		-	1.09	-	V	
V <sub>OL</sub>	LOW-level output voltage	$V_{I} = V_{IH} \text{ or } V_{IL}; I_{O} = 3 \text{ mA}; V_{CCO} = 1.2 \text{ V}$		-	0.07	-	V	
l <sub>l</sub>	input leakage current	DIR input; V <sub>I</sub> = 0 V to 5.5 V; V <sub>CCI</sub> = 1.2 V to 5.5 V		-	-	±1	μA	
I <sub>BHL</sub>	bus hold LOW current	A or B port; $V_I$ = 0.42 V; $V_{CCI}$ = 1.2 V		-	19	-	μA	
I <sub>BHH</sub>	bus hold HIGH current	A or B port; V <sub>I</sub> = 0.78 V; V <sub>CCI</sub> = 1.2 V		-	-19	-	μA	
I <sub>BHLO</sub>	bus hold LOW overdrive current	A or B port; V <sub>CCI</sub> = 1.2 V	[3]	-	19	-	μA	
I <sub>BHHO</sub>	bus hold HIGH overdrive current	A or B port; V <sub>CCI</sub> = 1.2 V	[3]	-	-19	-	μA	
I <sub>OZ</sub>	OFF-state output current	A or B port; $V_0 = 0$ V or $V_{CCO}$ ; $V_{CCO} = 1.2$ V to 5.5 V		-	-	±1	μA	
I <sub>OFF</sub>	power-off leakage current	A port; V <sub>1</sub> or V <sub>0</sub> = 0 V to 5.5 V; V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 1.2 V to 5.5 V		-	-	±1	μA	
		B port; V <sub>1</sub> or V <sub>0</sub> = 0 V to 5.5 V; V <sub>CC(B)</sub> = 0 V; V <sub>CC(A)</sub> = 1.2 V to 5.5 V		-	-	±1	μA	
CI	input capacitance	DIR input; $V_1 = 0 V \text{ or } 3.3 V$ ; $V_{CC(A)} = V_{CC(B)} = 3.3 V$		-	2.2	-	pF	
C <sub>I/O</sub>	input/output capacitance	A and B port; suspend mode; V <sub>O</sub> = 3.3 V or 0 V; V <sub>CC(A)</sub> = V <sub>CC(B)</sub> = 3.3 V		-	6.0	-	pF	

[1]  $V_{CCI}$  is the supply voltage associated with the data input port.

[2] V<sub>CCO</sub> is the supply voltage associated with the output port.

[3] To guarantee the node switches, an external driver must source/sink at least  $I_{BHLO}/I_{BHHO}$  when the input is in the range  $V_{IL}$  to  $V_{IH}$ .

#### Table 8. Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V). [1] [2]

Symbol	Parameter	Conditions	-40 °C to	+85 °C	-40 °C to	+125 °C	Unit
			Min	Мах	Min	Мах	
V <sub>IH</sub>	HIGH-level	data input					
	input voltage	V <sub>CCI</sub> = 1.2 V	0.8V <sub>CCI</sub>	-	0.8V <sub>CCI</sub>	-	V
		V <sub>CCI</sub> = 1.4 V to 1.95 V	0.65V <sub>CCI</sub>	-	0.65V <sub>CCI</sub>	-	V
		V <sub>CCI</sub> = 2.3 V to 2.7 V	1.7	-	1.7	-	V
		V <sub>CCI</sub> = 3.0 V to 3.6 V	2.0	-	2.0	-	V
		V <sub>CCI</sub> = 4.5 V to 5.5 V	0.7V <sub>CCI</sub>	-	0.7V <sub>CCI</sub>	-	V
		DIR input					
		V <sub>CCI</sub> = 1.2 V	0.8V <sub>CC(A)</sub>	-	0.8V <sub>CC(A)</sub>	-	V
		V <sub>CCI</sub> = 1.4 V to 1.95 V	0.65V <sub>CC(A)</sub>	-	0.65V <sub>CC(A)</sub>	-	V
		V <sub>CCI</sub> = 2.3 V to 2.7 V	1.7	-	1.7	-	V
		V <sub>CCI</sub> = 3.0 V to 3.6 V	2.0	-	2.0	-	V
		V <sub>CCI</sub> = 4.5 V to 5.5 V	0.7V <sub>CC(A)</sub>	-	0.7V <sub>CC(A)</sub>	-	V

Symbol	Parameter	Conditions	-40 °C to	o +85 °C	-40 °C to	+125 °C	Unit
			Min	Max	Min	Max	1
VIL	LOW-level	data input					
	input voltage	V <sub>CCI</sub> = 1.2 V	-	0.2V <sub>CCI</sub>	-	0.2V <sub>CCI</sub>	V
		V <sub>CCI</sub> = 1.4 V to 1.95 V	-	0.35V <sub>CCI</sub>	-	0.35V <sub>CCI</sub>	V
		V <sub>CCI</sub> = 2.3 V to 2.7 V	-	0.7	-	0.7	V
		V <sub>CCI</sub> = 3.0 V to 3.6 V	-	0.8	-	0.8	V
		V <sub>CCI</sub> = 4.5 V to 5.5 V	-	0.3V <sub>CCI</sub>	-	0.3V <sub>CCI</sub>	V
		DIR input					
		V <sub>CCI</sub> = 1.2 V	-	0.2V <sub>CC(A)</sub>	-	0.2V <sub>CC(A)</sub>	V
		V <sub>CCI</sub> = 1.4 V to 1.95 V	-	0.35V <sub>CC(A)</sub>	-	0.35V <sub>CC(A)</sub>	V
		V <sub>CCI</sub> = 2.3 V to 2.7 V	-	0.7	-	0.7	V
		V <sub>CCI</sub> = 3.0 V to 3.6 V	-	0.8	-	0.8	V
		V <sub>CCI</sub> = 4.5 V to 5.5 V	-	0.3V <sub>CC(A)</sub>	-	0.3V <sub>CC(A)</sub>	V
V <sub>OH</sub> HIGH-level		$V_{I} = V_{IH}$					
	output voltage	$I_{O}$ = -100 µA; $V_{CCO}$ = 1.2 V to 4.5 V	V <sub>CCO</sub> - 0.1	-	V <sub>CCO</sub> - 0.1	-	V
		I <sub>O</sub> = -6 mA; V <sub>CCO</sub> = 1.4 V	1.0	-	1.0	-	V
		I <sub>O</sub> = -8 mA; V <sub>CCO</sub> = 1.65 V	1.2	-	1.2	-	V
		I <sub>O</sub> = -12 mA; V <sub>CCO</sub> = 2.3 V	1.9	-	1.9	-	V
		I <sub>O</sub> = -24 mA; V <sub>CCO</sub> = 3.0 V	2.4	_	2.4	-	V
		I <sub>O</sub> = -32 mA; V <sub>CCO</sub> = 4.5 V	3.8	-	3.8	-	V
V <sub>OL</sub>	LOW-level	$V_{I} = V_{IL}$					
	output voltage	$I_0$ = 100 µA; $V_{CCO}$ = 1.2 V to 4.5 V	-	0.1	-	0.1	V
		I <sub>O</sub> = 6 mA; V <sub>CCO</sub> = 1.4 V	-	0.3	-	0.3	V
		I <sub>O</sub> = 8 mA; V <sub>CCO</sub> = 1.65 V	-	0.45	-	0.45	V
		I <sub>O</sub> = 12 mA; V <sub>CCO</sub> = 2.3 V	-	0.3	-	0.3	V
		I <sub>O</sub> = 24 mA; V <sub>CCO</sub> = 3.0 V	-	0.55	-	0.55	V
		I <sub>O</sub> = 32 mA; V <sub>CCO</sub> = 4.5 V	-	0.55	-	0.55	V
I	input leakage current	DIR input; $V_I = 0 V$ to 5.5 V; $V_{CCI} = 1.2 V$ to 5.5 V	-	±2	-	±10	μA
BHL	bus hold LOW	A or B port					
	current	V <sub>I</sub> = 0.49 V; V <sub>CCI</sub> = 1.4 V	15	-	10	-	μA
		V <sub>I</sub> = 0.58 V; V <sub>CCI</sub> = 1.65 V	25	-	20	-	μA
		V <sub>I</sub> = 0.70 V; V <sub>CCI</sub> = 2.3 V	45	-	45	-	μA
		V <sub>I</sub> = 0.80 V; V <sub>CCI</sub> = 3.0 V	100	-	80	-	μA
		V <sub>I</sub> = 1.35 V; V <sub>CCI</sub> = 4.5 V	100	-	100	-	μA
внн	bus hold HIGH	A or B port					
	current	V <sub>I</sub> = 0.91 V; V <sub>CCI</sub> = 1.4 V	-15	-	-10	-	μA
		V <sub>I</sub> = 1.07 V; V <sub>CCI</sub> = 1.65 V	-25	-	-20	-	μΑ
		V <sub>1</sub> = 1.60 V; V <sub>CC1</sub> = 2.3 V	-45	_	-45	-	μA
		$V_1 = 2.00 \text{ V}; V_{CC1} = 3.0 \text{ V}$	-100	-	-80	-	μA
		$V_1 = 3.15 \text{ V}; V_{CC1} = 4.5 \text{ V}$	-100	_	-100	_	μA

Symbol	Parameter	Conditions		-40 °C to	o +85 °C	-40 °C to +125 °C		Unit
				Min	Max	Min	Max	
I <sub>BHLO</sub>	bus hold LOW	A or B port	[3]					
	overdrive	V <sub>CCI</sub> = 1.6 V		125	-	125	-	μA
	current	V <sub>CCI</sub> = 1.95 V		200	-	200	-	μA
		V <sub>CCI</sub> = 2.7 V		300	-	300	-	μA
		V <sub>CCI</sub> = 3.6 V		500	-	500	-	μA
		V <sub>CCI</sub> = 5.5 V		900	-	900	-	μA
I <sub>BHHO</sub>	bus hold HIGH	A or B port	[3]					
	overdrive current	V <sub>CCI</sub> = 1.6 V		-125	-	-125	-	μA
	current	V <sub>CCI</sub> = 1.95 V		-200	-	-200	-	μA
		V <sub>CCI</sub> = 2.7 V		-300	-	-300	-	μA
		V <sub>CCI</sub> = 3.6 V		-500	-	-500	-	μA
		V <sub>CCI</sub> = 5.5 V		-900	-	-900	-	μA
I <sub>OZ</sub>	OFF-state output current	A or B port; $V_0 = 0$ V or $V_{CCO}$ ; $V_{CCO} = 1.2$ V to 5.5 V		-	±2	-	±10	μA
I <sub>OFF</sub>	power-off leakage	A port; V <sub>I</sub> or V <sub>O</sub> = 0 V to 5.5 V; V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 1.2 V to 5.5 V		-	±2	-	±10	μA
	current	B port; V <sub>1</sub> or V <sub>0</sub> = 0 V to 5.5 V; V <sub>CC(B)</sub> = 0 V; V <sub>CC(A)</sub> = 1.2 V to 5.5 V		-	±2	-	±10	μA
I <sub>CC</sub>	supply current	A port; $V_I = 0$ V or $V_{CCI}$ ; $I_O = 0$ A						
		V <sub>CC(A)</sub> , V <sub>CC(B)</sub> = 1.2 V to 5.5 V		-	8	-	8	μA
		V <sub>CC(A)</sub> , V <sub>CC(B)</sub> = 1.65 V to 5.5 V		-	3	-	3	μA
		V <sub>CC(A)</sub> = 5.5 V; V <sub>CC(B)</sub> = 0 V		-	2	-	2	μA
		V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 5.5 V		-2	-	-2	-	μA
		B port; $V_I = 0 V$ or $V_{CCI}$ ; $I_O = 0 A$						
		V <sub>CC(A)</sub> , V <sub>CC(B)</sub> = 1.2 V to 5.5 V		-	8	-	8	μA
		V <sub>CC(A)</sub> , V <sub>CC(B)</sub> = 1.65 V to 5.5 V		-	3	-	3	μA
		V <sub>CC(B)</sub> = 5.5 V; V <sub>CC(A)</sub> = 0 V		-	2	-	2	μA
		V <sub>CC(B)</sub> = 0 V; V <sub>CC(A)</sub> = 5.5 V		-2	-	-2	-	μA
		A plus B port ( $I_{CC(A)} + I_{CC(B)}$ ); $I_O = 0$ A; V <sub>I</sub> = 0 V or V <sub>CCI</sub>						
		V <sub>CC(A)</sub> , V <sub>CC(B)</sub> = 1.2 V to 5.5 V		-	16	-	16	μA
		V <sub>CC(A)</sub> , V <sub>CC(B)</sub> = 1.65 V to 5.5 V		-	4	-	4	μA
ΔI <sub>CC</sub>	additional	$V_{CC(A)}$ , $V_{CC(B)}$ = 3.0 V to 5.5 V						
	supply current	A port; A port at $V_{CC(A)}$ - 0.6 V; DIR at $V_{CC(A)}$ ; B port = open	[4]	-	50	-	75	μA
		DIR input; DIR at $V_{CC(A)}$ - 0.6 V; A port at $V_{CC(A)}$ or GND; B port = open		-	50	-	75	μA
		B port; B port at V <sub>CC(B)</sub> - 0.6 V; DIR at GND; A port = open	[4]	-	50	-	75	μA

[1]  $V_{CCI}$  is the supply voltage associated with the data input port.

[2] V<sub>CCO</sub> is the supply voltage associated with the output port.

[3] To guarantee the node switches, an external driver must source/sink at least IBHLO/IBHHO when the input is in the range VIL to VIH.

[4] For non bus hold parts only (74LVC1T45-Q100).

# **11. Dynamic characteristics**

Symbol	Parameter	Conditions		V <sub>CC(B)</sub>					
			1.2 V	1.5 V	1.8 V	2.5 V	3.3 V	5.0 V	
t <sub>PLH</sub>	LOW to HIGH	A to B	10.6	8.1	7.0	5.8	5.3	5.1	ns
	propagation delay	B to A	10.6	9.5	9.0	8.5	8.3	8.2	ns
t <sub>PHL</sub>	HIGH to LOW	A to B	10.1	7.1	6.0	5.3	5.2	5.4	ns
	propagation delay	B to A	10.1	8.6	8.1	7.8	7.6	7.6	ns
t <sub>PHZ</sub>	HIGH to OFF-state propagation delay	DIR to A	9.4	9.4	9.4	9.4	9.4	9.4	ns
		DIR to B	12.0	9.4	9.0	7.8	8.4	7.9	ns
t <sub>PLZ</sub>	LOW to OFF-state	DIR to A	7.1	7.1	7.1	7.1	7.1	7.1	ns
	propagation delay	DIR to B	9.5	7.8	7.7	6.9	7.6	7.0	ns
t <sub>PZH</sub>	OFF-state to HIGH	DIR to A [1	] 20.1	17.3	16.7	15.4	15.9	15.2	ns
	propagation delay	DIR to B [1	] 17.7	15.2	14.1	12.9	12.4	12.2	ns
t <sub>PZL</sub>	OFF-state to LOW	DIR to A [1	] 22.1	18.0	17.1	15.6	16.0	15.5	ns
	propagation delay	DIR to B [1	] 19.5	16.5	15.4	14.7	14.6	14.8	ns

**Table 9. Typical dynamic characteristics at V**<sub>CC(A)</sub> = 1.2 V and T<sub>amb</sub> = 25 °C Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 7; for waveforms see Fig. 5 and Fig. 6

[1] t<sub>PZH</sub> and t<sub>PZL</sub> are calculated values using the formula shown in <u>Section 13.4</u>

## Table 10. Typical dynamic characteristics at $V_{CC(B)}$ = 1.2 V and $T_{amb}$ = 25 $^{\circ}C$

Voltages are referenced to GND (ground = 0 V); for test circuit see  $\frac{\text{Fig. 7}}{1000}$ ; for waveforms see  $\frac{\text{Fig. 5}}{1000}$  and  $\frac{\text{Fig. 6}}{10000}$ .

Symbol	Parameter	Conditions			Vc	C(A)			Unit
			1.2 V	1.5 V	1.8 V	2.5 V	3.3 V	5.0 V	
t <sub>PLH</sub>	LOW to HIGH	A to B	10.6	9.5	9.0	8.5	8.3	8.2	ns
	propagation delay	B to A	10.6	8.1	7.0	5.8	5.3	5.1	ns
t <sub>PHL</sub>	HIGH to LOW	A to B	10.1	8.6	8.1	7.8	7.6	7.6	ns
	propagation delay	B to A	10.1	7.1	6.0	5.3	5.2	5.4	ns
t <sub>PHZ</sub>	HIGH to OFF-state propagation delay	DIR to A	9.4	6.5	5.7	4.1	4.1	3.0	ns
		DIR to B	12.0	6.1	5.4	4.6	4.3	4.0	ns
t <sub>PLZ</sub>	LOW to OFF-state propagation delay	DIR to A	7.1	4.9	4.5	3.2	3.4	2.5	ns
		DIR to B	9.5	7.3	6.6	5.9	5.7	5.6	ns
t <sub>PZH</sub>	OFF-state to HIGH	DIR to A [1]	20.1	15.4	13.6	11.7	11.0	10.7	ns
	propagation delay	DIR to B [1]	17.7	14.4	13.5	11.7	11.7	10.7	ns
t <sub>PZL</sub>	OFF-state to LOW	DIR to A [1]	22.1	13.2	11.4	9.9	9.5	9.4	ns
pro	propagation delay	DIR to B [1]	19.5	15.1	13.8	11.9	11.7	10.6	ns

[1]  $t_{PZH}$  and  $t_{PZL}$  are calculated values using the formula shown in <u>Section 13.4</u>

## Table 11. Typical power dissipation capacitance at $V_{CC(A)}$ = $V_{CC(B)}$ and $T_{amb}$ = 25 $^{\circ}C$

Voltages are referenced to GND (ground = 0 V). [1] [2]

Symbol	Parameter	Conditions	$V_{CC(A)}$ and $V_{CC(B)}$						
			1.8 V	2.5 V	3.3 V	5.5 V			
C <sub>PD</sub>	power dissipation capacitance	A port: (direction A to B); B port: (direction B to A)	2	3	3	4	pF		
		A port: (direction B to A); B port: (direction A to B)	15	16	16	18	pF		

[1]  $C_{PD}$  is used to determine the dynamic power dissipation (P<sub>D</sub> in  $\mu$ W).

 $P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma (C_L \times V_{CC}^2 \times f_o)$  where:

f<sub>i</sub> = input frequency in MHz;

 $f_o$  = output frequency in MHz;

 $C_L$  = load capacitance in pF;

 $V_{CC}$  = supply voltage in V;

N = number of inputs switching;

 $\Sigma(C_L \times V_{CC}^2 \times f_o)$  = sum of the outputs.

[2]  $f_i = 10$  MHz;  $V_I = GND$  to  $V_{CC}$ ;  $t_r = t_f = 1$  ns;  $C_L = 0$  pF;  $R_L = \infty \Omega$ .

### Table 12. Dynamic characteristics for temperature range -40 °C to +85 °C

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 7; for wave forms see Fig. 5 and Fig. 6

Symbol	Parameter	Conditions					Vc	C(B)					Unit
			1.5 V ± 0.1 V		1.8 V ± 0.15 V		2.5 V ± 0.2 V		3.3 V ± 0.3 V		5.0 V ± 0.5 V		
			Min	Мах	Min	Max	Min	Max	Min	Max	Min	Мах	
V <sub>CC(A)</sub> =	1.4 V to 1.6 V												
t <sub>PLH</sub>	LOW to HIGH propagation delay	A to B	2.8	21.3	2.4	17.6	2.0	13.5	1.7	11.8	1.6	10.5	ns
		B to A	2.8	21.3	2.6	19.1	2.3	14.9	2.3	12.4	2.2	12.0	ns
t <sub>PHL</sub>	HIGH to LOW	A to B	2.6	19.3	2.2	15.3	1.8	11.8	1.7	10.9	1.7	10.8	ns
propagation delay	B to A	2.6	19.3	2.4	17.3	2.3	13.2	2.2	11.3	2.3	11.0	ns	
t <sub>PHZ</sub>	HIGH to OFF-state	DIR to A	3.0	18.7	3.0	18.7	3.0	18.7	3.0	18.7	3.0	18.7	ns
	propagation delay	DIR to B	3.5	24.8	3.5	23.6	3.0	11.0	3.3	11.3	2.8	10.3	ns
t <sub>PLZ</sub>	LOW to OFF-state	DIR to A	2.4	11.4	2.4	11.4	2.4	11.4	2.4	11.4	2.4	11.4	ns
	propagation delay	DIR to B	2.8	18.3	3.0	17.2	2.5	9.4	3.0	10.1	2.5	9.4	ns
t <sub>PZH</sub>	OFF-state to HIGH	DIR to A [1]	-	39.6	-	36.3	-	24.3	-	22.5	-	21.4	ns
	propagation delay	DIR to B [1]	-	32.7	-	29.0	-	24.9	-	23.2	-	21.9	ns
t <sub>PZL</sub>	OFF-state to LOW	DIR to A [1]	-	44.1	-	40.9	-	24.2	-	22.6	-	21.3	ns
	propagation delay	DIR to B [1]	-	38.0	-	34.0	-	30.5	-	29.6	-	29.5	ns

Symbol	Parameter	Conditions					Vc	C(B)					Unit
				5 V .1 V		8 V 15 V	2.	5 V .2 V		3 V .3 V		0 V .5 V	
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Мах	1
V <sub>CC(A)</sub> =	1.65 V to 1.95 V	1		1							1		
t <sub>PLH</sub>	LOW to HIGH	A to B	2.6	19.1	2.2	17.7	2.2	9.3	1.7	7.2	1.4	6.8	ns
	propagation delay	B to A	2.4	17.6	2.2	17.7	2.3	16.0	2.1	15.5	1.9	15.1	ns
t <sub>PHL</sub>	HIGH to LOW	A to B	2.4	17.3	2.0	14.3	1.6	8.5	1.8	7.1	1.7	7.0	ns
	propagation delay	B to A	2.2	15.3	2.0	14.3	2.1	12.9	2.0	12.6	1.8	12.2	ns
t <sub>PHZ</sub>	HIGH to OFF-state	DIR to A	2.9	17.1	2.9	17.1	2.9	17.1	2.9	17.1	2.9	17.1	ns
	propagation delay	DIR to B	3.2	24.1	3.2	21.9	2.7	11.5	3.0	10.3	2.5	8.2	ns
t <sub>PLZ</sub>	LOW to OFF-state	DIR to A	2.4	10.5	2.4	10.5	2.4	10.5	2.4	10.5	2.4	10.5	ns
	propagation delay	DIR to B	2.5	17.6	2.6	16.0	2.2	9.2	2.7	8.4	2.4	6.4	ns
t <sub>PZH</sub>	OFF-state to HIGH	DIR to A [1]	-	35.2	-	33.7	-	25.2	-	23.9	-	21.8	ns
	propagation delay	DIR to B [1]	-	29.6	-	28.2	-	19.8	-	17.7	-	17.3	ns
t <sub>PZL</sub>	OFF-state to LOW	DIR to A [1]	-	39.4	-	36.2	-	24.4	-	22.9	-	20.4	ns
	propagation delay	DIR to B [1]	-	34.4	-	31.4	-	25.6	-	24.2	-	24.1	ns
$V_{CC(A)} =$	2.3 V to 2.7 V												
t <sub>PLH</sub>	LOW to HIGH	A to B	2.3	17.9	2.3	16.0	1.5	8.5	1.3	6.2	1.1	4.8	ns
	propagation delay	B to A	2.0	13.5	2.2	9.3	1.5	8.5	1.4	8.0	1.0	7.5	ns
t <sub>PHL</sub>	HIGH to LOW propagation delay	A to B	2.3	15.8	2.1	12.9	1.4	7.5	1.3	5.4	0.9	4.6	ns
		B to A	1.8	11.8	1.9	8.5	1.4	7.5	1.3	7.0	0.9	6.2	ns
t <sub>PHZ</sub>	HIGH to OFF-state	DIR to A	2.1	8.1	2.1	8.1	2.1	8.1	2.1	8.1	2.1	8.1	ns
	propagation delay	DIR to B	3.0	22.5	3.0	21.4	2.5	11.0	2.8	9.3	2.3	6.9	ns
t <sub>PLZ</sub>	LOW to OFF-state	DIR to A	1.7	5.8	1.7	5.8	1.7	5.8	1.7	5.8	1.7	5.8	ns
	propagation delay	DIR to B	2.3	14.6	2.5	13.2	2.0	9.0	2.5	8.4	1.8	5.3	ns
t <sub>PZH</sub>	OFF-state to HIGH	DIR to A [1]	-	28.1	-	22.5	-	17.5	-	16.4	-	12.8	ns
	propagation delay	DIR to B [1]	-	23.7	-	21.8	-	14.3	-	12.0	-	10.6	ns
t <sub>PZL</sub>	OFF-state to LOW	DIR to A [1]	-	34.3	-	29.9	-	18.5	-	16.3	-	13.1	ns
	propagation delay	DIR to B [1]	-	23.9	-	21.0	-	15.6	-	13.5	-	12.7	ns
$V_{CC(A)} =$	3.0 V to 3.6 V												
t <sub>PLH</sub>	LOW to HIGH	A to B	2.3	17.1	2.1	15.5	1.4	8.0	0.8	5.6	0.7	4.4	ns
	propagation delay	B to A	1.7	11.8	1.7	7.2	1.3	6.2	0.7	5.6	0.6	5.4	ns
t <sub>PHL</sub>	HIGH to LOW	A to B	2.2	15.6	2.0	12.6	1.3	7.0	0.8	5.0	0.7	4.0	ns
	propagation delay	B to A	1.7	10.9	1.8	7.1	1.3	5.4	0.8	5.0	0.7	4.5	ns
t <sub>PHZ</sub>	HIGH to OFF-state	DIR to A	2.3	7.3	2.3	7.3	2.3	7.3	2.3	7.3	2.7	7.3	ns
	propagation delay	DIR to B	2.9	18.0	2.9	16.5	2.3	10.1	2.7	8.6	2.2	6.3	ns
t <sub>PLZ</sub>	LOW to OFF-state	DIR to A	2.0	5.6	2.0	5.6	2.0	5.6	2.0	5.6	2.0	5.6	ns
	propagation delay	DIR to B	2.3	13.6	2.4	12.5	1.9	7.8	2.3	7.1	1.7	4.9	ns
t <sub>PZH</sub>	OFF-state to HIGH	DIR to A [1]	-	25.4	-	19.7	-	14.0	-	12.7	-	10.3	ns
	propagation delay	DIR to B [1]	-	22.7	-	21.1	-	13.6	-	11.2	-	10.0	ns
t <sub>PZL</sub>	OFF-state to LOW	DIR to A [1]	-	28.9	-	23.6	-	15.5	-	13.6	-	10.8	ns
	propagation delay	DIR to B [1]	-	22.9	-	19.9	-	14.3	-	12.3	-	11.3	ns

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Symbol	Parameter	Conditions					Vc	C(B)					Unit
		-	1.5 V ± 0.1 V		1.8 V ± 0.15 V		2.5 V ± 0.2 V		3.3 V ± 0.3 V		5.0 V ± 0.5 V		
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
V <sub>CC(A)</sub> =	4.5 V to 5.5 V					1					1		
t <sub>PLH</sub>	LOW to HIGH	A to B	2.2	16.6	1.9	15.1	1.0	7.5	0.7	5.4	0.5	3.9	ns
	propagation delay	B to A	1.6	10.5	1.4	6.8	1.0	4.8	0.7	4.4	0.5	3.9	ns
t <sub>PHL</sub>		A to B	2.3	15.3	1.8	12.2	1.0	6.2	0.7	4.5	0.5	3.5	ns
propagation delay	B to A	1.7	10.8	1.7	7.0	0.9	4.6	0.7	4.0	0.5	3.5	ns	
t <sub>PHZ</sub>	HIGH to OFF-state	DIR to A	1.7	5.4	1.7	5.4	1.7	5.4	1.7	5.4	1.7	5.4	ns
	propagation delay	DIR to B	2.9	17.3	2.9	16.1	2.3	9.7	2.7	8.0	2.5	5.7	ns
t <sub>PLZ</sub>	LOW to OFF-state	DIR to A	1.4	3.7	1.4	3.7	1.3	3.7	1.0	3.7	0.9	3.7	ns
	propagation delay	DIR to B	2.3	13.1	2.4	12.1	1.9	7.4	2.3	7.0	1.8	4.5	ns
t <sub>PZH</sub>	OFF-state to HIGH	DIR to A [1]	-	23.6	-	18.9	-	12.2	-	11.4	-	8.4	ns
	propagation delay	DIR to B [1]	-	20.3	-	18.8	-	11.2	-	9.1	-	7.6	ns
t <sub>PZL</sub>	propagation dolay	DIR to A [1]	-	28.1	-	23.1	-	14.3	-	12.0	-	9.2	ns
		DIR to B [1]	-	20.7	-	17.6	-	11.6	-	9.9	-	8.9	ns

[1]  $t_{PZH}$  and  $t_{PZL}$  are calculated values using the formula shown in <u>Section 13.4</u>

## Table 13. Dynamic characteristics for temperature range -40 °C to +125 °C

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 7; for wave forms see Fig. 5 and Fig. 6

Symbol	Parameter	Conditions					Vc	C(B)					Unit
		-	1.5 V ± 0.1 V		1.8 V ± 0.15 V		2.5 V ± 0.2 V		3.3 V ± 0.3 V		5.0 V ± 0.5 V		
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Мах	
V <sub>CC(A)</sub> =	1.4 V to 1.6 V												
t <sub>PLH</sub>	LOW to HIGH propagation delay	A to B	2.5	23.5	2.1	19.4	1.8	14.9	1.5	13.0	1.4	11.6	ns
		B to A	2.5	23.5	2.3	21.1	2.0	16.4	2.0	13.7	1.9	13.2	ns
t <sub>PHL</sub>	HIGH to LOW	A to B	2.3	21.3	1.9	16.9	1.6	13.0	1.5	12.0	1.5	11.9	ns
propagation delay	B to A	2.3	21.3	2.1	19.1	2.0	14.6	1.9	12.5	2.0	12.1	ns	
t <sub>PHZ</sub>	HIGH to OFF-state	DIR to A	2.7	20.6	2.7	20.6	2.7	20.6	2.7	20.6	2.7	20.6	ns
	propagation delay	DIR to B	3.1	27.3	3.1	26.0	2.7	12.1	2.9	12.5	2.5	11.4	ns
t <sub>PLZ</sub>	LOW to OFF-state	DIR to A	2.1	12.6	2.1	12.6	2.1	12.6	2.1	12.6	2.1	12.6	ns
	propagation delay	DIR to B	2.5	20.2	2.7	19.0	2.2	10.4	2.7	11.2	2.2	10.4	ns
t <sub>PZH</sub>	OFF-state to HIGH	DIR to A [1]	-	43.7	-	40.1	-	26.8	-	24.9	-	23.6	ns
	propagation delay	DIR to B [1]	-	36.1	-	32.0	-	27.5	-	25.6	-	24.2	ns
t <sub>PZL</sub>	OFF-state to LOW	DIR to A [1]	-	48.6	-	45.1	-	26.7	-	25.0	-	23.5	ns
	propagation delay	DIR to B [1]	-	41.9	-	37.5	-	33.6	-	32.6	-	32.5	ns

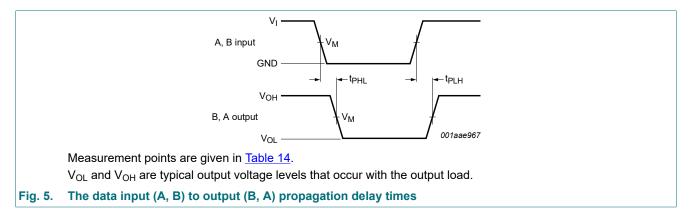
Symbol	Parameter	Conditions					Vc	C(B)					Unit
				5 V .1 V		8 V 15 V	2.	5 V .2 V		3 V .3 V		0 V .5 V	-
			Min	Max									
V <sub>CC(A)</sub> =	1.65 V to 1.95 V												
t <sub>PLH</sub>	LOW to HIGH	A to B	2.3	21.1	1.9	19.5	1.9	10.3	1.5	8.0	1.2	7.5	ns
	propagation delay	B to A	2.1	19.4	1.9	19.5	2.0	17.6	1.8	17.1	1.7	16.7	ns
t <sub>PHL</sub>	HIGH to LOW	A to B	2.1	19.1	1.8	15.8	1.4	9.4	1.6	7.9	1.5	7.7	ns
	propagation delay	B to A	1.9	16.9	1.8	15.8	1.8	14.2	1.8	13.9	1.6	13.5	ns
t <sub>PHZ</sub>	HIGH to OFF-state	DIR to A	2.6	18.9	2.6	18.9	2.6	18.9	2.6	18.9	2.6	18.9	ns
	propagation delay	DIR to B	2.8	26.6	2.8	24.1	2.4	12.7	2.7	11.4	2.2	9.1	ns
t <sub>PLZ</sub>	LOW to OFF-state	DIR to A	2.1	11.6	2.1	11.6	2.1	11.6	2.1	11.6	2.1	11.6	ns
	propagation delay	DIR to B	2.2	19.4	2.3	17.6	1.9	10.2	2.4	9.3	2.1	7.4	ns
t <sub>PZH</sub>	OFF-state to HIGH	DIR to A [1]	-	38.8	-	37.1	-	27.8	-	26.4	-	24.1	ns
	propagation delay	DIR to B [1]	-	32.7	-	31.1	-	21.9	-	19.6	-	19.1	ns
t <sub>PZL</sub>	OFF-state to LOW	DIR to A [1]	-	43.5	-	39.9	-	26.9	-	25.3	-	22.6	ns
	propagation delay	DIR to B [1]	-	38.0	-	34.7	-	28.3	-	26.8	-	26.6	ns
$V_{CC(A)} =$	2.3 V to 2.7 V												
t <sub>PLH</sub>	LOW to HIGH	A to B	2.0	19.7	2.0	17.6	1.3	9.4	1.1	6.9	0.9	5.3	ns
	propagation delay	B to A	1.8	14.9	1.9	10.3	1.3	9.4	1.2	8.8	0.9	8.3	ns
t <sub>PHL</sub>	HIGH to LOW propagation delay	A to B	2.0	17.4	1.8	14.2	1.2	8.3	1.1	6.0	0.8	5.1	ns
		B to A	1.6	13.0	1.7	9.4	1.2	8.3	1.1	7.7	0.8	6.9	ns
t <sub>PHZ</sub>	HIGH to OFF-state	DIR to A	1.8	9.0	1.8	9.0	1.8	9.0	1.8	9.0	1.8	9.0	ns
	propagation delay	DIR to B	2.7	24.8	2.7	23.6	2.2	12.1	2.5	10.3	2.0	7.6	ns
t <sub>PLZ</sub>	LOW to OFF-state	DIR to A	1.5	6.4	1.5	6.4	1.5	6.4	1.5	6.4	1.5	6.4	ns
	propagation delay	DIR to B	2.0	16.1	2.2	14.6	1.8	9.9	2.2	9.3	1.6	5.9	ns
t <sub>PZH</sub>	OFF-state to HIGH	DIR to A [1]	-	31.0	-	24.9	-	19.3	-	18.1	-	14.2	ns
	propagation delay	DIR to B [1]	-	26.1	-	24.0	-	15.8	-	13.3	-	11.7	ns
t <sub>PZL</sub>	OFF-state to LOW	DIR to A [1]	-	37.8	-	33.0	-	20.4	-	18.0	-	14.5	ns
	propagation delay	DIR to B [1]	-	26.4	-	23.2	-	17.3	-	15.0	-	14.1	ns
$V_{CC(A)} =$	3.0 V to 3.6 V												
t <sub>PLH</sub>	LOW to HIGH	A to B	2.0	18.9	1.8	17.1	1.2	8.8	0.7	6.2	0.6	4.9	ns
	propagation delay	B to A	1.5	13.0	1.5	8.0	1.1	6.9	0.6	6.2	0.5	6.0	ns
t <sub>PHL</sub>	HIGH to LOW	A to B	1.9	17.2	1.8	13.9	1.1	7.7	0.7	5.5	0.6	4.4	ns
	propagation delay	B to A	1.5	12.0	1.6	7.9	1.1	6.0	0.7	5.5	0.6	5.0	ns
t <sub>PHZ</sub>	HIGH to OFF-state	DIR to A	2.0	8.1	2.0	8.1	2.0	8.1	2.0	8.1	2.4	8.1	ns
	propagation delay	DIR to B	2.6	19.8	2.6	18.2	2.0	11.2	2.4	9.5	1.9	7.0	ns
t <sub>PLZ</sub>	LOW to OFF-state	DIR to A	1.8	6.2	1.8	6.2	1.8	6.2	1.8	6.2	1.8	6.2	ns
	propagation delay	DIR to B	2.0	15.0	2.1	13.8	1.7	8.6	2.0	7.9	1.5	5.4	ns
t <sub>PZH</sub>	OFF-state to HIGH	DIR to A [1]	-	28.0	-	21.8	-	15.5	-	14.1	-	11.4	ns
	propagation delay	DIR to B [1]	-	25.1	-	23.3	-	15.0	-	12.4	-	11.1	ns
t <sub>PZL</sub>	OFF-state to LOW	DIR to A [1]	-	31.8	-	26.1	-	17.2	-	15.0	-	12.0	ns
	propagation delay	DIR to B [1]	-	25.3	-	22.0	-	15.8	-	13.6	-	12.5	ns

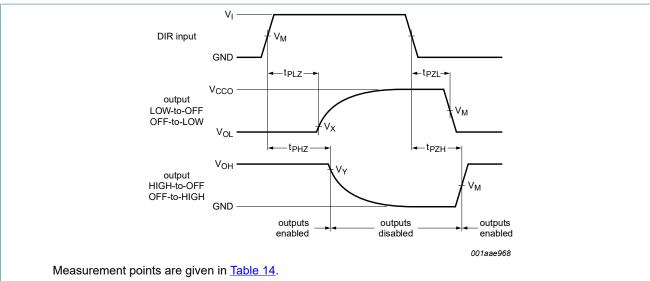
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Symbol	Parameter	Conditions	V <sub>CC(B)</sub>										Unit
		-	1.5 V ± 0.1 V		1.8 V ± 0.15 V		2.5 V ± 0.2 V		3.3 V ± 0.3 V		5.0 V ± 0.5 V		
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
V <sub>CC(A)</sub> =	4.5 V to 5.5 V										1		
t <sub>PLH</sub>	LOW to HIGH propagation delay	A to B	1.9	18.3	1.7	16.7	0.9	8.3	0.6	6.0	0.4	4.3	ns
		B to A	1.4	11.6	1.2	7.5	0.9	5.3	0.6	4.9	0.4	4.3	ns
t <sub>PHL</sub>		A to B	2.0	16.9	1.6	13.5	0.9	6.9	0.6	5.0	0.4	3.9	ns
propagation delay	propagation delay	B to A	1.5	11.9	1.5	7.7	0.8	5.1	0.6	4.4	0.4	3.9	ns
t <sub>PHZ</sub>	HIGH to OFF-state	DIR to A	1.5	6.0	1.5	6.0	1.5	6.0	1.5	6.0	1.5	6.0	ns
	propagation delay	DIR to B	2.6	19.1	2.6	17.8	2.0	10.7	2.4	8.8	2.2	6.3	ns
t <sub>PLZ</sub>	LOW to OFF-state	DIR to A	1.2	4.1	1.2	4.1	1.1	4.1	0.9	4.1	0.8	4.1	ns
	propagation delay	DIR to B	2.0	14.5	2.1	13.4	1.7	8.2	2.0	7.7	1.6	5.0	ns
t <sub>PZH</sub>	OFF-state to HIGH propagation delay	DIR to A [1]	-	26.1	-	20.9	-	13.5	-	12.6	-	9.3	ns
		DIR to B [1]	-	22.4	-	20.8	-	12.4	-	10.1	-	8.4	ns
t <sub>PZL</sub>	OFF-state to LOW	DIR to A [1]	-	31.0	-	25.5	-	15.8	-	13.2	-	10.2	ns
	propagation delay	DIR to B [1]	-	22.9	-	19.5	-	12.9	-	11.0	-	9.9	ns

[1]  $t_{PZH}$  and  $t_{PZL}$  are calculated values using the formula shown in <u>Section 13.4</u>

## 11.1. Waveforms and test circuit





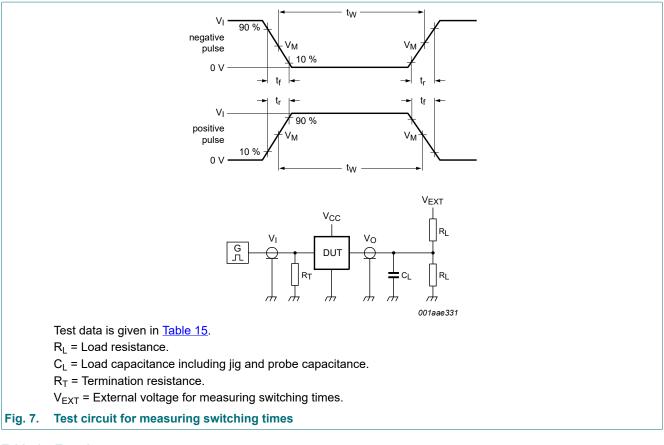
V<sub>OL</sub> and V<sub>OH</sub> are typical output voltage levels that occur with the output load.

#### Fig. 6. Enable and disable times

Supply voltage	Input [1]	Output [2]	Output [2]				
V <sub>CC(A)</sub> , V <sub>CC(B)</sub>	V <sub>M</sub>	V <sub>M</sub>	V <sub>X</sub>	V <sub>Y</sub>			
1.2 V to 1.6 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.1 V	V <sub>OH</sub> - 0.1 V			
1.65 V to 2.7 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> - 0.15 V			
3.0 V to 5.5 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.3 V	V <sub>OH</sub> - 0.3 V			

[1]  $V_{CCI}$  is the supply voltage associated with the data input port.

[2] V<sub>CCO</sub> is the supply voltage associated with the output port.



## Table 15. Test data

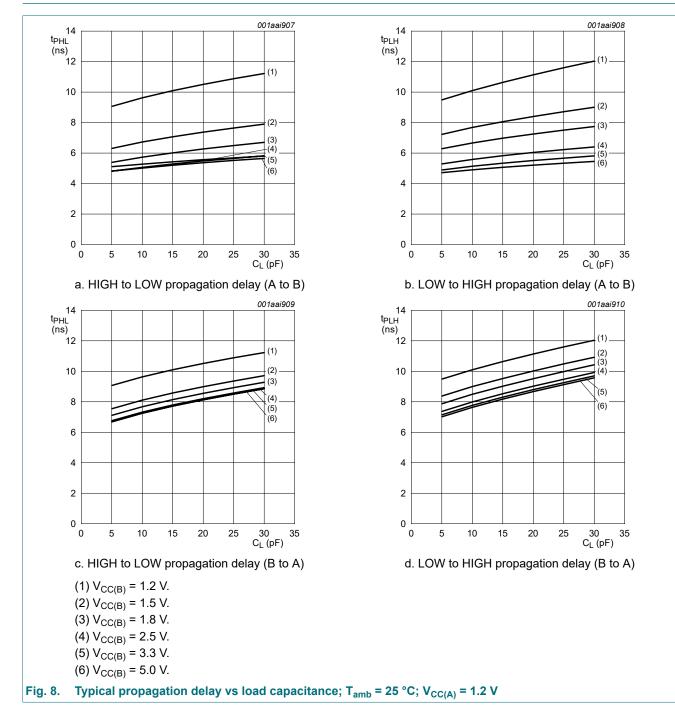
Supply voltage	Input		Load		V <sub>EXT</sub>				
$V_{CC(A)}, V_{CC(B)}$	V <sub>I</sub> [1]	Δt/ΔV [2]	CL	RL	t <sub>PLH</sub> , t <sub>PHL</sub>	t <sub>PZH</sub> , t <sub>PHZ</sub>	t <sub>PZL</sub> , t <sub>PLZ</sub> [3]		
1.2 V to 5.5 V	V <sub>CCI</sub>	≤ 1.0 ns/V	15 pF	2 kΩ	open	GND	2V <sub>CCO</sub>		

[1]  $V_{CCI}$  is the supply voltage associated with the data input port.

[2] dV/dt ≥ 1.0 V/ns

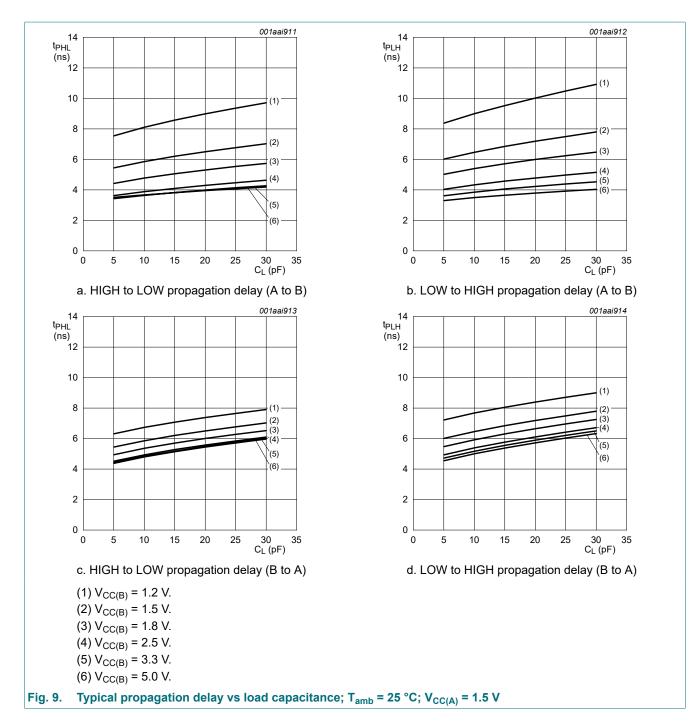
[3]  $V_{CCO}$  is the supply voltage associated with the output port.

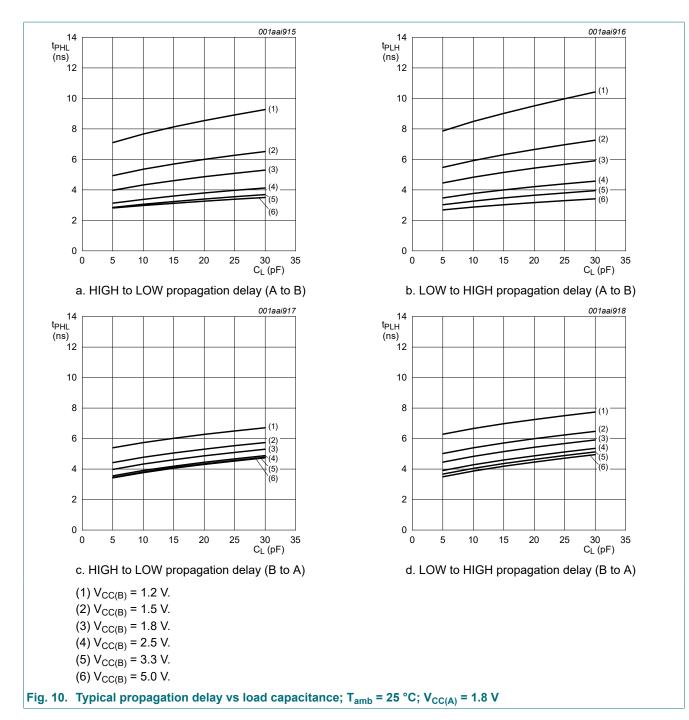
74LVC\_LVCH1T45\_Q100

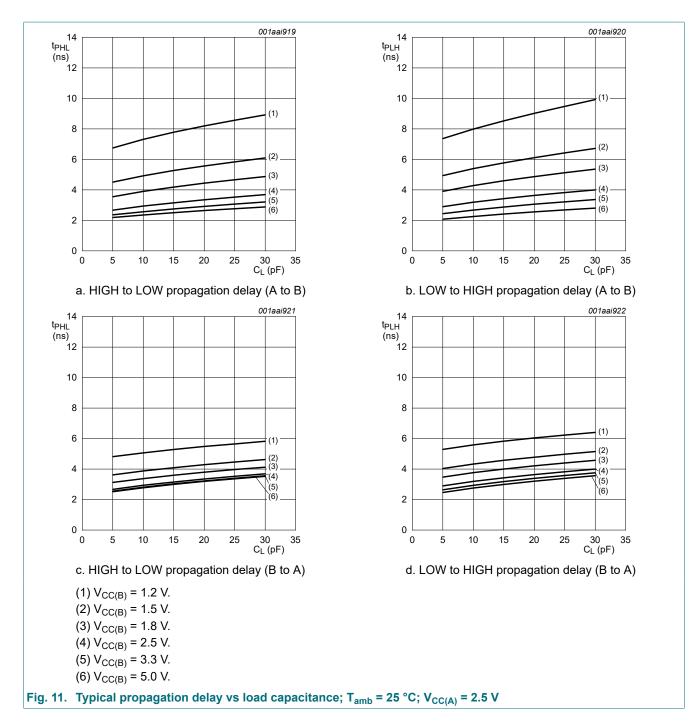


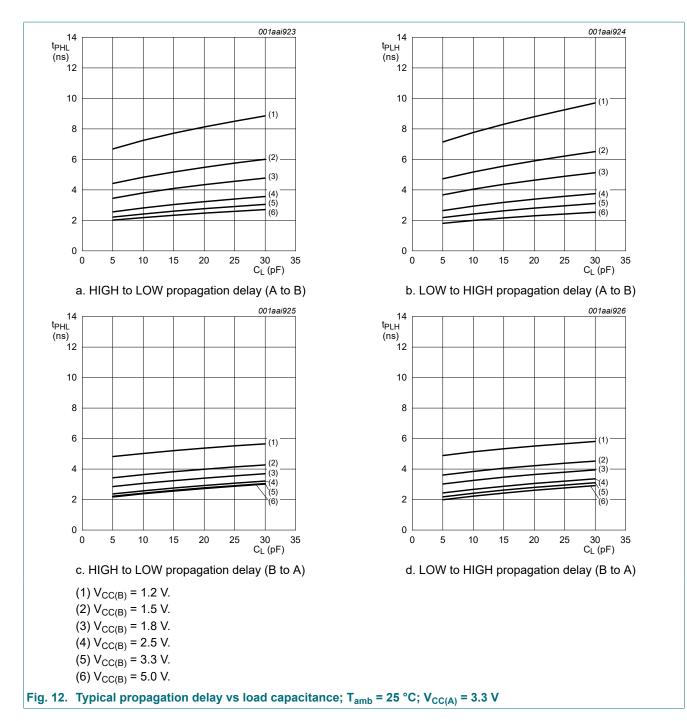
# 12. Typical propagation delay characteristics

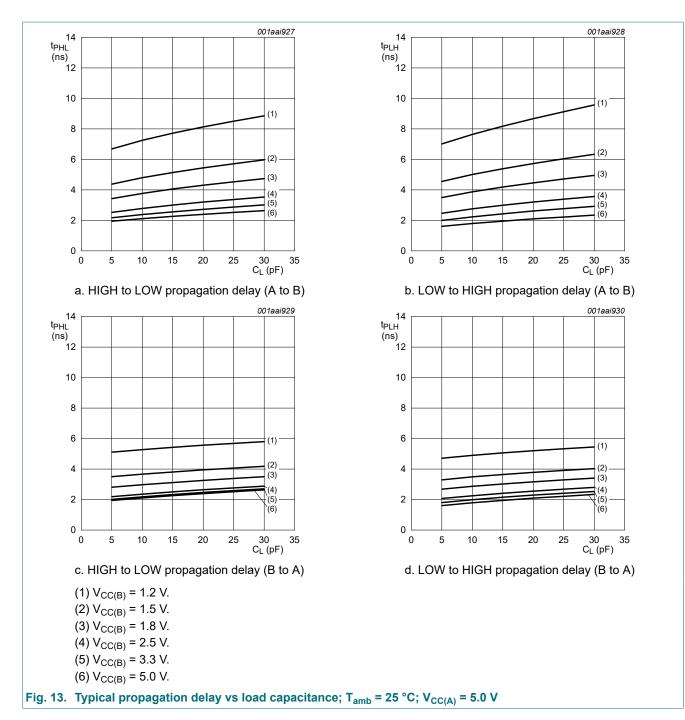
74LVC\_LVCH1T45\_Q100











# **13. Application information**

## 13.1. Unidirectional logic level-shifting application

The circuit given in Fig. 14 is an example of the 74LVC1T45-Q100; 74LVCH1T45-Q100 being used in a unidirectional logic level-shifting application.

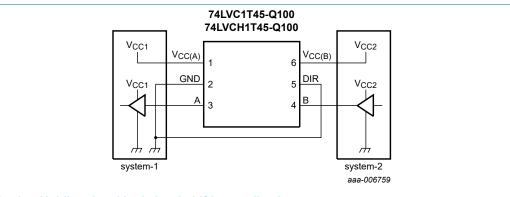


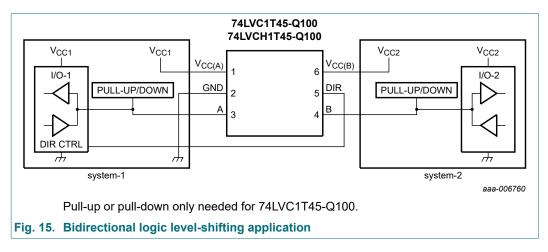
Fig. 14. Unidirectional logic level-shifting application

|--|

Pin	Name	Function	Description
1	V <sub>CC(A)</sub>	V <sub>CC1</sub>	supply voltage of system-1 (1.2 V to 5.5 V)
2	GND	GND	device GND
3	A	OUT	output level depends on V <sub>CC1</sub> voltage
4	В	IN	input threshold value depends on $V_{CC2}$ voltage
5	DIR	DIR	the GND (LOW level) determines B port to A port direction
6	V <sub>CC(B)</sub>	V <sub>CC2</sub>	supply voltage of system-2 (1.2 V to 5.5 V)

## 13.2. Bidirectional logic level-shifting application

Fig. 15 shows the 74LVC1T45-Q100; 74LVCH1T45-Q100 being used in a bidirectional logic level-shifting application. Since the device does not have an output enable pin, the system designer should take precautions to avoid bus contention between system-1 and system-2 when changing directions.



<u>Table 17</u> provides a sequence that illustrates data transmission from system-1 to system-2 and then from system-2 to system-1.

Table 17. Description bidirectional l	ogic level-shifting application
---------------------------------------	---------------------------------

H = HIGH voltage level; L = LOW voltage level; Z = high-impedance OFF-state.

State	DIR CTRL	I/O-1	I/O-2	Description
1	Н	output	input	system-1 data to system-2
2	Н	Z	Z	system-2 is getting ready to send data to system-1. I/O-1 and I/O-2 are disabled. The bus-line state depends on bus hold.
3	L	Z	Z	DIR bit is set LOW. I/O-1 and I/O-2 are still disabled. The bus-line state depends on bus hold.
4	L	input	output	system-2 data to system-1

## 13.3. Power-up considerations

The device is designed such that no special power-up sequence is required other than GND being applied first.

V <sub>CC(A)</sub>	V <sub>CC(B)</sub>	V <sub>CC(B)</sub>					
	0 V	1.8 V	2.5 V	3.3 V	5.0 V		
0 V	0	< 1	< 1	< 1	< 1	μΑ	
1.8 V	< 1	< 2	< 2	< 2	2	μΑ	
2.5 V	< 1	< 2	< 2	< 2	< 2	μΑ	
3.3 V	< 1	< 2	< 2	< 2	< 2	μΑ	
5.0 V	< 1	2	< 2	< 2	< 2	μΑ	

Table 18. Typical total supply current (I<sub>CC(A)</sub> + I<sub>CC(B)</sub>)

## 13.4. Enable times

Calculate the enable times for the 74LVC1T45-Q100; 74LVCH1T45-Q100 using the following formulas:

- $t_{PZH}$  (DIR to A) =  $t_{PLZ}$  (DIR to B) +  $t_{PLH}$  (B to A)
- $t_{PZL}$  (DIR to A) =  $t_{PHZ}$  (DIR to B) +  $t_{PHL}$  (B to A)
- $t_{PZH}$  (DIR to B) =  $t_{PLZ}$  (DIR to A) +  $t_{PLH}$  (A to B)
- $t_{PZL}$  (DIR to B) =  $t_{PHZ}$  (DIR to A) +  $t_{PHL}$  (A to B)

In a bidirectional application, these enable times provide the maximum delay from the time the DIR bit is switched until an output is expected. For example, if the 74LVC1T45-Q100; 74LVCH1T45-Q100 initially is transmitting from A to B, then the DIR bit is switched, the B port of the device must be disabled before presenting it with an input. After the B port has been disabled, an input signal applied to it appears on the corresponding A port after the specified propagation delay.

# 14. Package outline

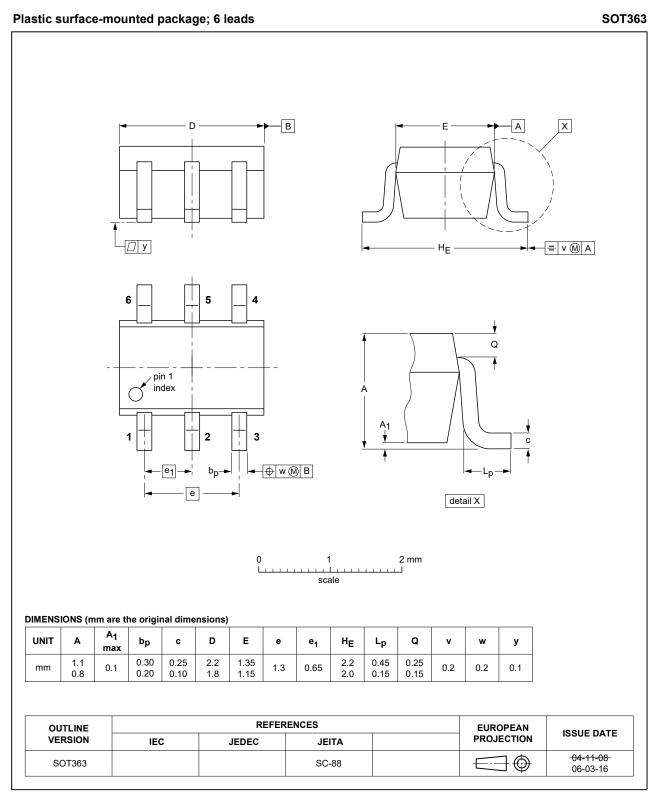


Fig. 16. Package outline SOT363 (SC-88)

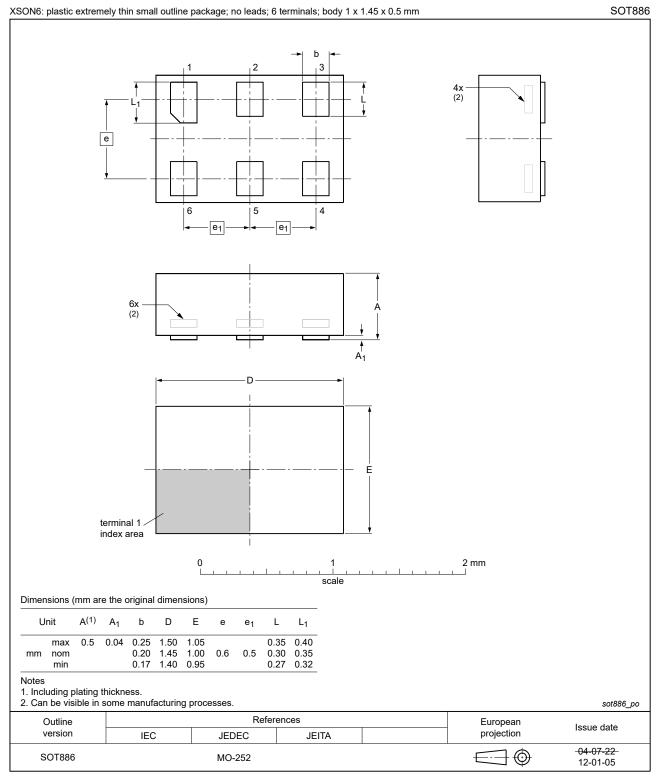


Fig. 17. Package outline SOT886 (XSON6)

# **15. Abbreviations**

Table 19. Abbreviations			
Acronym	Description		
CDM	Charged Device Model		
DUT	Device Under Test		
ESD	ElectroStatic Discharge		
HBM	Human Body Model		

# 16. Revision history

## Table 20. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes		
74LVC_LVCH1T45_Q100 v.4	20201201	Product data sheet	-	74LVC_LVCH1T45_Q100 v.3		
Modifications:	<ul> <li><u>Section 2</u>: ESD specification aligned with Non-Automotive data sheet.</li> <li><u>Table 5</u>: Derating values for P<sub>tot</sub> total power dissipation updated.</li> </ul>					
74LVC_LVCH1T45_Q100 v.3	20190319	Product data sheet	-	74LVC_LVCH1T45_Q100 v.2		
Modifications:	<ul> <li>The format of this data sheet has been redesigned to comply with the identity guidelines of Nexperia.</li> <li>Legal texts have been adapted to the new company name where appropriate.</li> <li>Type number 74LVC1T45GM-Q100 (XSON6/SOT886) added.</li> </ul>					
74LVC_LVCH1T45_Q100 v.2	20160530	Product data sheet	-	74LVC_LVCH1T45_Q100 v.1		
Modifications:	<u>Table 1</u> : typo corrected in type number					
74LVC_LVCH1T45_Q100 v.1	20130328	Product data sheet	-	-		

# 17. Legal information

#### **Data sheet status**

Document status [1][2]	Product status [3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

 Please consult the most recently issued document before initiating or completing a design.

- [2] The term 'short data sheet' is explained in section "Definitions".
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